

Quantum Mechanics

Graduate course

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Textbook: Quantum mechanics concepts and applications
(2nd edition)

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topics: Most materials from chps 6-11 will be covered

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Chapter 6: Three-dimensional motion

sections 6.1 and 6.2 are self study [3D problems in Cartesian coordinates]

section 6.3: 3D problems in spherical coordinates:

consider a particle moving in 3d under the potential $V(x, y, z)$, then the schrodinger equation takes the form

$$i\hbar \frac{\partial \Psi}{\partial t} = H \Psi \quad ; \text{ where } H = \frac{P^2}{2m} + V(\vec{r}) \quad ;$$

now in 3d \vec{p} is given by $\vec{p} = \frac{\hbar}{i} \vec{\nabla}$; $p_x = \frac{\hbar}{i} \frac{d}{dx}$

\Rightarrow the schrodinger eqⁿ becomes

$$p_y = \frac{\hbar}{i} \frac{d}{dy}$$

$$i\hbar \frac{\partial \Psi}{\partial t} = -\frac{\hbar^2}{2m} \nabla^2 \Psi + V \Psi \quad \dots (1)$$

$$p_z = \frac{\hbar}{i} \frac{d}{dz}$$

where ∇^2 is the Laplacian

now if the potential V is independent of time, then the general solution of equation (1) is given by

$$\Psi_n(\vec{r}, t) = \psi_n(\vec{r}) e^{-i \frac{E_n t}{\hbar}} \quad \text{-----} \quad (2)$$

by substituting (2) in (1), we end up with the time-independent Schrodinger equation

$$-\frac{\hbar^2}{2m} \nabla^2 \psi + V(\vec{r}) \psi = E \psi \quad \text{-----} \quad (3)$$

in this course we will be discussing mostly spherically symmetric potentials (central fields) where $V(\vec{r}) = V(r)$

four types of potentials will be studied

- 1) The free particle $V(r) = 0$
- 2) The spherical square potential well $V(r) = \begin{cases} -V_0, & r < a \\ 0, & r > a \end{cases}$
- 3) The Isotropic Harmonic oscillator $V(r) = \frac{1}{2} m \omega^2 r^2$
 $\hookrightarrow (\omega_x = \omega_y = \omega_z = \omega)$
- 4) The Coulomb potential (H atom) $V(r) = \frac{-e^2}{r}$

now since the Hamiltonian is spherically symmetric, we are going to use the spherical coordinates (r, θ, ϕ) , where

$$x = r \sin \theta \cos \phi, \quad y = r \sin \theta \sin \phi, \quad z = r \cos \theta$$

in spherical coordinates, ∇^2 is given by

$$\begin{aligned} \nabla^2 &= \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2}{\partial \phi^2} \\ &= \frac{1}{r^2} \left[\frac{\partial}{\partial r} \left(r^2 \frac{\partial}{\partial r} \right) + \frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial}{\partial \theta} \right) + \frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \phi^2} \right] \text{ see appendix B.3} \\ &= -L^2 / \hbar^2 \text{ angular part} \end{aligned}$$

$$\Rightarrow \nabla^2 = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial}{\partial r} \right) - \frac{L^2}{r^2 \hbar^2} \quad ; \text{ substitute this into eq (3)}$$

$$\Rightarrow -\frac{\hbar^2}{2m} \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial}{\partial r} \right) \psi(r) + \frac{L^2}{2mr^2} \psi(r) + V(r) \psi(r) = E \psi(r) \quad (4)$$

since the Hamiltonian is a sum of radial part and angular part, ~~then~~ we can look for solutions that are products of radial and angular part, that is

$$\psi_{nlm}(r, \theta, \phi) = R_{nl}(r) Y_{lm}(\theta, \phi) \quad \dots (5)$$

Substituting this solution into the Schrödinger equation (4) we have

$$-\frac{\hbar^2}{2m} Y_{lm} \frac{1}{r^2} \frac{d}{dr} \left(r^2 \frac{dR_{nl}}{dr} \right) + \left[V(r) + \frac{L^2}{2mr^2} \right] R_{nl} Y_{lm} = E R_{nl} Y_{lm}$$

Now using $L^2 Y_{lm} = \hbar^2 l(l+1) Y_{lm}$, we have

$$-\frac{\hbar^2}{2m} Y_{lm} \frac{1}{r^2} \left(r^2 \frac{dR_{nl}}{dr} \right) + \left[V(r) + \frac{\hbar^2 l(l+1)}{2mr^2} \right] R_{nl} Y_{lm} = E R_{nl} Y_{lm}$$

divide by Y_{lm} and rearrange

$$\frac{1}{r^2} \frac{d}{dr} \left(r^2 \frac{dR_{nl}}{dr} \right) + \frac{2m}{\hbar^2} \left[E - V(r) - \frac{\hbar^2 l(l+1)}{2mr^2} \right] R_{nl} = 0$$

multiply by r ,

$$\frac{1}{r} \frac{d}{dr} \left(r^2 \frac{dR_{nl}}{dr} \right) + \frac{2m}{\hbar^2} \left[E - V(r) - \frac{\hbar^2 l(l+1)}{2mr^2} \right] r R_{nl} = 0$$

↓ can be written as

$$\frac{d^2}{dr^2} (r R_{nl}) + \frac{2m}{\hbar^2} \left[E - V(r) - \frac{\hbar^2 l(l+1)}{2mr^2} \right] (r R_{nl}) = 0$$

$$\Rightarrow \frac{d^2}{dr^2} (r R_{nl}) + \frac{2m}{\hbar^2} [E - V_{\text{eff}}(r)] r R_{nl} = 0 \quad \dots (6)$$

where $V_{\text{eff}}(r) = V(r) + \frac{\hbar^2 L(L+1)}{2mr^2}$ effective potential

\swarrow Central potential
 \searrow repulsive or centrifugal potential (tend to repel the particle away from the center)

equation (6) is called the radial equation

Let $U_{nl}(r) = r R_{nl}(r) \Rightarrow$ the radial eqⁿ becomes

$$\frac{d^2 U_{nl}(r)}{dr^2} + K_l(r) U_{nl}(r) = 0 \quad (7) \quad \text{where } K_l(r) = \frac{2m}{\hbar^2} (E - V_{\text{eff}})$$

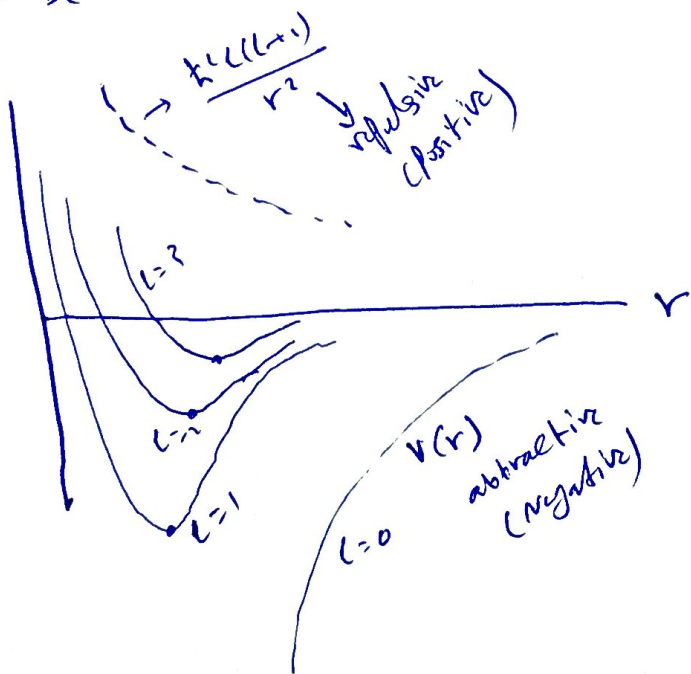
\Rightarrow 1D motion with $0 < r < \infty$

notice that the wavefunction $\psi(r)$ must be finite for all values of r ($0 < r < \infty$), so if $R_{nl}(r)$ is finite \Rightarrow

$U_{nl}(r) = r R_{nl}(r)$ must vanish at $r=0$

- for equation (7) to describe bound states, the potential $V(r)$

must be attractive (i.e. negative) because $\frac{\hbar^2 L(L+1)}{r^2}$ is repulsive.



We see that as L increases, the depth of V_{eff} decreases and minimum moves to the right away from the center. The farther the particle from the center, the less bound it will be.

Remark: when a particle has orbital and spin degrees of freedom, its total wave function is

$$\Psi_{n, l, m_l, m_s}(\vec{r}) = Y_{n, l, m_l}(\vec{r}) |s, m_s\rangle = R_{nl}(r) Y_{lm_l}(\theta, \phi) \boxed{|s, m_s\rangle}$$

here, the spin operator \hat{S} acts only on the spin part $|s, m_s\rangle$ sometimes called χ
the orbital operator \hat{L} acts only on the spatial part Y_{lm}